Claims:

1	1.	. A digital imaging system comprising:			
2		a.	an in	nage sensor;	
3		b.	an or	ientation sensor; and	
4 ·		c.	an in	nage manipulator adapted to:	
5			i)	receive image sensor orientation;	
6			ii)	receive image orientation; and	
7			iii)	adjust the image orientation.	
1	2.	A di	digital imaging system comprising:		
2		a.	an in	nage sensor configured to sense an image subject and to capture a	
3	preser	presentation of the image;			
4		b.	an or	rientation sensor configured to sense changes in the orientation of an	
5	image with respect to the base line orientation coordinates; and				
6		c.	an in	nage manipulator adapted to:	
7			i)	receive image sensor orientation from the image sensor;	
8			ii)	receive image orientation from the orientation sensor; and	
9			iii)	adjust the image orientation in relation to the baseline orientation	
10	coordinates.				
1	3.	The	e digital imaging system of claim 1 wherein the digital imaging system is		
2	chose	chosen from the group consisting of still cameras and video cameras.			
1	4.	The digital imaging system of claim 1 wherein the image sensor is a charge			
2	couple	coupled device array.			
1	5.	The	The digital imaging system of claim 1 wherein the orientation sensor is chosen		
2	from t	from the group consisting of electronic gyroscopic sensors, mechanical gyroscopic			
3	sensor	sensors, and optical gyroscopic sensors.			

2 an image rotation system. 1 7. A digital camera comprising: 2 a. a charge coupled device image sensor; 3 b. a gyroscopic camera orientation sensor; and 4 c. an image manipulator adapted to: 5 i) receive image sensor orientation; 6 ii) receive image orientation; and 7 iii) rotate the image. 1 8. The digital camera of claim 6 wherein the digital camera is chosen from the group 2 consisting of still cameras and video cameras.

The digital imaging sensor of claim 1 wherein the image manipulator comprises

The digital camera of claim 6 wherein the gyroscopic orientation sensor is chosen

from the group consisting of electronic gyroscopic sensors, mechanical gyroscopic

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sensors, and optical gyroscopic sensors.

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